Robot Specification of Team ZJUDancer

- Robot name
  ZJUDancer
- Height of the robot
  680mm
- Weight of the robot
  4.7kg
- Walking speed in cm/s
  30cm/s
- Number of degrees of freedom and type of motors on each kinematic chain of the robot
  There are 18 degrees of freedom in ZJUDancer robot.
  Dynamixel MX-106, MX-64 and MX-28 servo.
- Type of sensors used(incl. type of camera(s))
  The type of camera is UI-1221LE-C-HQ.
  The type of IMU is ADIS16405BMLZ.
  The type of feet force sensor is CZL-YB-46B/10kg.
- Computing unit(s)
  The computing unit is NVIDIA Jetson TX2 board.